

METEK®

RGS08 Linear Rail for Heavier Weight Applications

with 57000 Series Size 23 Single and Double Stack Hybrid Linear Actuators

A combination of Haydon Kerk Motion Solutions patented motion technologies into a single integrated, linear motion control system. RGS linear rails feature standard wear-compensating, anti-backlash driven carriages to insure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications.

Technical specifications for 57000 Series Size 23 Hybrid Linear Actuator Stepper Motors are on page 3.

To determine what is best for your application see the Linear Rail Applications Checklist.

RGS08 57000 Series Size 23 Double Stack

Identifying the RGS08 Part Number Codes when Ordering

RG	S	08	К —	М	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	S = Standard	08 = 50 lbs (222 N) (Maximum static load)	K = TFE Kerkote® X = Special (example: Kerkote with grease)	$\mathbf{M} = Motorized$	0098 = .098-in (2.50) 0100 = .100-in (2.54) 0197 = .197-in (5.00) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 0630 = .630-in (16.00) 1000 = 1.000-in (25.4)	Suffix used to identify specific motors (43000 Single/ Double Stack – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

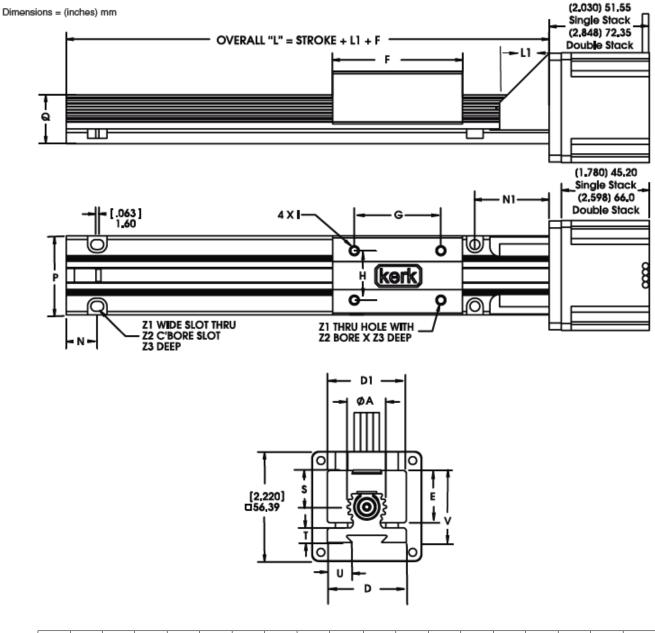
Carriage holes available in Metric sizes M3, M4, M5, M6

AMETEK®

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RGS08 with 57000 Series Size 23 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 50 lbs (222 N)



	Α	D	D1	Е	F	G	Н	l*	L1	Ν	N1	Р	Q	S	Т	U	V	Z1	Z2	Z3
(inch)	(0.8)	(1.6)	(1.6)	(1.06)	(2.7)	(1.75)	(1.0)	10-20	(1.0)	(0.625)	(1.5)	(1.25)	(1.0)	(0.74)	(0.3)	(0.51)	(1.47)	(0.2)	(0.33)	(0.19)
mm	20.3	40.6	40.6	26.9	68.6	44.5	25.4	UNC	25.4	15.9	38.1	15.9	25.4	18.8	7.6	12.9	37.3	5.1	8.4	4.8

* Metric threads also available for carriage.

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Single Stack

57000 Series Size 23

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)										
Wiring		Bipolar	Unipo	olar**						
Winding Voltage	3.25 VDC	5 VDC	5 VDC	12 VDC						
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A					
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω					
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH					
Power Consumption	13 W									
Rotor Inertia	166 gcm ²									
Insulation Class		Class B (Class F available)								
Weight		18 oz (511 g)								
Insulation Resistance	20 ΜΩ									

Standard motors are Class B rated for maximum temperature of 130°C.

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Double Stack

57000 Series Size 23

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)										
Wiring		Bipolar								
Winding Voltage	3.25 VDC	5 VDC	12 VDC							
Current (RMS)/phase	3.85 A	2.5 A	1 A							
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω							
Inductance/phase	2.3 mH	7.6 mH	35.0 mH							
Power Consumption	25 W Total									
Rotor Inertia		321 gcm ²								
Insulation Class	Class B (Class F available)									
Weight	32 oz (958 g)									
Insulation Resistance	20 MΩ									

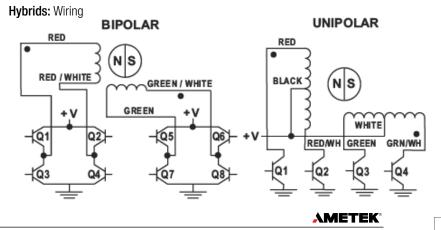


Size 23 57000 Series • Stepping Sequence & Wiring

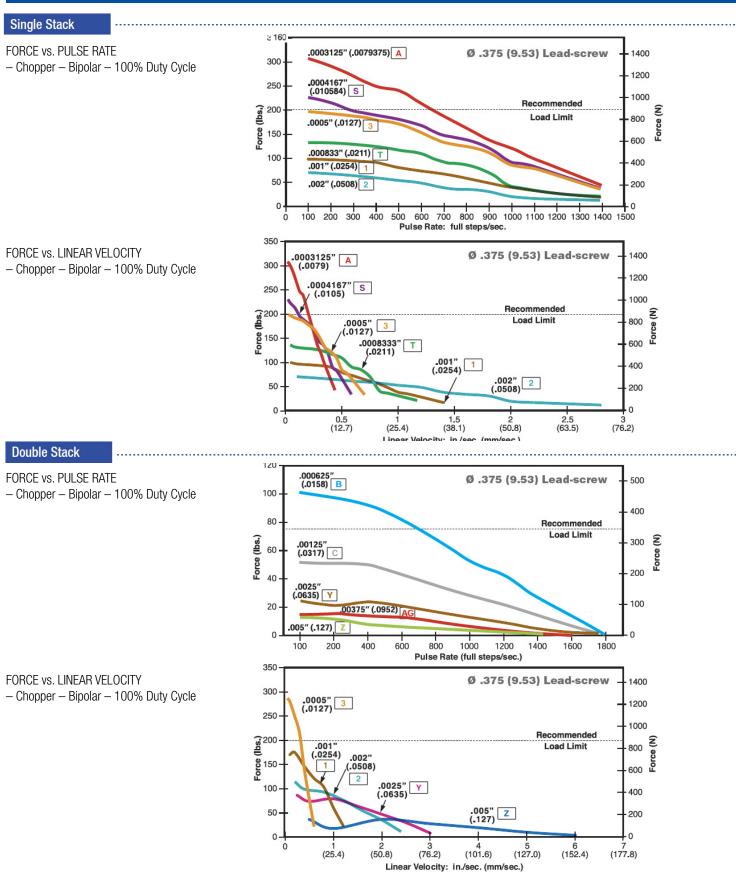
		Hybri	ds: Steppii	ng Sequen	се	
EXTEND CW	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
	Unipolar	Q1	Q2	Q3	Q4	
	Step					CCW
	1	ON	OFF	ON	OFF	
	2	OFF	ON	ON	OFF	DAC
	3	OFF	ON	OFF	ON	RFTRACT
	4	ON	OFF	OFF	ON	
	1	ON	OFF	ON	OFF]
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Note: Half stepping is accomplished by inserting an off state between transitioning phases.

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RGS Series • RGS08 Motorized • Size 23 57000 Series • Performance Curves



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot. With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

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